

ConfigurationDesk/RTI

Compatibility with Toolboxes and Blocksets Provided by MathWorks

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How to Contact dSPACE Support

There are different ways to contact dSPACE Support:

- Visit our Web site at <http://www.dspace.com/goto?support>
- Send an e-mail or phone:
 - General Technical Support:
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 - SystemDesk Support:
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- Use the dSPACE Installation Manager:
 - On your dSPACE DVD at `\Tools\InstallationManager.exe`
 - Via Start – Programs – dSPACE Installation Manager (after installation of the dSPACE software)
 - At <http://www.dspace.com/goto?im>

You can always find the latest version of the dSPACE Installation Manager here.

dSPACE recommends that you use the dSPACE Installation Manager to contact dSPACE Support.

Software Updates and Patches

dSPACE strongly recommends that you download and install the most recent patches for your current dSPACE installation. Visit <http://www.dspace.de/goto?support> for software updates and patches.

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Introduction

The compatibility information in this document covers dSPACE Release 2013-B and MATLAB® releases R2012a or higher.

For information on which dSPACE releases support which MATLAB releases, see: <http://www.dspace.com/goto?Versions>

Compatibility of MathWorks blocksets and toolboxes with Configuration Desk/RTI

In addition to MATLAB® and Simulink®, MathWorks® offers a wide range of blocksets and toolboxes which are extensions to the basic MATLAB and Simulink software packages.

Blocksets and toolboxes provide additional Simulink blocks. To be used with ConfigurationDesk or RTI, these blocks must support code generation with Simulink Coder™.



Only known compatibility issues specific to ConfigurationDesk / RTI are listed in this document. For detailed information on which blocks do or do not support code generation with Simulink Coder, refer to the MATLAB help¹ or contact MathWorks.

We test the compatibility of blocksets and toolboxes that provide Simulink blocks with selected demo models taken from the MATLAB installation or with our own test models designed especially for this purpose. These tests do not cover the complete functionality range of the blocksets. The complexity resulting from the number of blocks and their possible parameterizations is far too large to guarantee tests with 100% coverage.



As a result, problems might occur even when we state that a certain blockset or toolbox is supported by ConfigurationDesk / RTI. For information on the known problems, see the blockset- or toolbox-specific chapters below or contact support@dspace.de.

¹ A list of blocksets that support code generation can be found under "Supported Products" in the Simulink Coder help.

Blocksets and toolboxes not listed in this document

Blocksets and toolboxes that provide Simulink blocks but are not listed in this document have not been tested with ConfigurationDesk / RTI. Therefore we cannot make any compatibility statements concerning these blocksets and toolboxes.

Compatibility of blocksets and toolboxes not from MathWorks

We cannot make any statement on the compatibility of blocksets and toolboxes that were not developed by MathWorks.

Overview

Legend

Supported The toolbox or blockset is supported (general limitations for use with Simulink Coder).

Not supported The toolbox or blockset is not supported.

Supported, but known issues The toolbox or blockset is supported, but there are restrictions or known problems specific to RTI or ConfigurationDesk. Click the blockset or toolbox hyperlink to get more information.

Blockset (Product Names as of R2013b)	Description
Aerospace Blockset™	Supported
Communications System Toolbox™	Supported
Control System Toolbox™	Supported
DSP System Toolbox™	Supported, but known issue. See <i>DSP System Toolbox</i>
Fixed Point Designer™	Supported
Fuzzy Logic Toolbox™	Supported
Neural Network Toolbox™	Supported
Parallel Computing Toolbox™	Supported, but known issue. See <i>Parallel Computing Toolbox / MATLAB Distributed Computing Server</i>
MATLAB Distributed Computing Server™	Not supported. See <i>Parallel Computing Toolbox / MATLAB Distributed Computing Server</i>
Simscape™, SimElectronics®, SimDriveline™, SimHydraulics® and SimMechanics™	Supported, but known issue. See <i>Simscape, SimElectronics, SimDriveline, SimHydraulics and SimMechanics</i>
SimPowerSystems™	Supported, but known issue. See SimPowerSystems
Simulink Control Design™	Supported
Stateflow®	Supported, but known issue. See <i>Stateflow</i>
System Identification Toolbox™	Not supported

Supported Blocksets with Known Issues

Parallel Computing Toolbox / MATLAB Distributed Computing Server

Parallel building of model reference hierarchies

Relevance

- MATLAB Releases: All relevant
- dSPACE Platforms: All
- ConfigurationDesk, RTI and RTI-MP

Description Simulink Coder can accelerate code generation for models containing large model reference hierarchies by building referenced models in parallel whenever possible. This parallel build feature is supported by ConfigurationDesk, RTI and RTI-MP.

The parallel building of model reference hierarchies using MATLAB Distributed Computing Server is not supported.

For details on the parallel build feature refer to the RTI Implementation Guide and the Simulink Coder User's Guide from MathWorks.

DSP System Toolbox

General limitations

Relevance

- MATLAB Releases: All relevant
- dSPACE Platforms: All
- ConfigurationDesk, RTI and RTI-MP

Description The UDP Send and UDP Receive blocks are not supported by ConfigurationDesk / RTI. These blocks need access to Microsoft® Windows® - dependent compiler library files, which are not available for dSPACE systems.

Trying to build a model containing UDP Send and UDP Receive blocks with a dSPACE target file will result in a compiler error.

Variable description file issues**Block parameter access via variable description file****Relevance**

- MATLAB Releases: All relevant
- dSPACE Platforms: All
- ConfigurationDesk, RTI and RTI-MP

Description Depending on the MATLAB release in use, it is possible that some block parameters are not accessible from the variable description file.

Simscape, SimElectronics, SimDriveline, SimHydraulics and SimMechanics

General limitations**SimElectronics, SimDriveline, SimHydraulics, SimMechanics, Simscape's Foundation Library Blocks****RTI-MP limitation****Relevance**

- MATLAB Releases: All relevant
- dSPACE Platforms: RTI1005 RTI1006
- RTI-MP

Description For RTI-MP, the following limitation applies: Simscape, SimDriveline, SimElectronics, SimHydraulics and SimMechanics blocks must not be inserted at the root level of a model. Otherwise one of the following problems will occur:

- The RTI-MP Multiprocessor Setup dialog cannot be opened.
- Connection lines are not copied during model separation.
- Model separation is aborted with an error message.

These problems do not occur if these blocks are contained in subsystems.

SimMechanics Second Generation**Relevance**

- MATLAB Releases: R2012a
- dSPACE Platforms: All
- ConfigurationDesk, RTI and RTI-MP

Description In MATLAB R2012a SimMechanics Second Generation blocks do not support code generation.

Variable description file issues**Special ports and parameters not available in the variable description file****Relevance**

- MATLAB Releases: All relevant
- dSPACE Platforms: All
- ConfigurationDesk, RTI and RTI-MP

Description Most Simscape, SimDriveline, SimElectronics, SimHydraulics and SimMechanics blocks are not connected by regular Simulink signals but by physical connection lines. These signals are not available in the variable description file.

Compiler issues
PowerPC compiler warnings**Relevance**

- MATLAB Releases: All relevant
- dSPACE Platforms: RTI1005 RTI1103 RTI1104 RTI1401
- RTI and RTI-MP

Description Applications with Simscape blocks can be built for dSPACE platforms based on a PowerPC processor. Even though the Microtec PowerPC compiler issues some warnings, the application can be loaded to the real-time hardware.

Real-time execution
Memory and performance constraints**Relevance**

- MATLAB Releases: All relevant
- dSPACE Platforms: All
- ConfigurationDesk, RTI and RTI-MP

Description The generated application for some models including blocks from the aforementioned Toolboxes might cause either memory or performance problems while running on the hardware, due to its size and complexity. To avoid this, reduce the size of the model and adjust the Solver and Task Configuration settings.

SimPowerSystems

General limitations**RTI-MP limitation****Relevance**

- MATLAB Releases: All relevant
- dSPACE Platforms: RTI1005 RTI1006
- RTI-MP

Description The SimPowerSystems Blockset makes extensive use of From and Goto tags with global scope to exchange simulation data. The use of these blocks can circumvent the multiprocessor data exchange mechanism implemented by interprocessor communication (IPC) blocks of the RTI-MP Blockset. This is why all parts of a multiprocessor Simulink model using the Power System Blockset should be assigned to one single processor.

SimPowerSystems blocks must not be inserted at the root level of an RTI-MP model**Relevance**

- MATLAB Releases: All relevant

- dSPACE Platforms: RTI1005 RTI1006
- RTI-MP

Description SimPowerSystems blocks must not be inserted at the root level of an RTI-MP model. Otherwise one of the following problems will occur:

- The RTI-MP Multiprocessor Setup dialog cannot be opened.
- Connection lines are not copied during model separation.
- Model separation is aborted with an error message.

These problems do not occur if the SimPowerSystems blocks are contained in subsystems.

Supercapacitor block

Relevance

- MATLAB Releases: R2013a
- dSPACE Platforms: All
- ConfigurationDesk, RTI and RTI-MP

Description The Supercapacitor block introduced with MATLAB R2013a is not supported by ConfigurationDesk / RTI. This block contains a trigonometric function block (asinh) which, according to the MathWorks Documentation, is not supported by all compilers.

Variable description file issues

Special ports and parameters not available in variable description file

Relevance

- MATLAB Releases: All relevant
- dSPACE Platforms: All
- ConfigurationDesk, RTI and RTI-MP

Description SimPowerSystems uses Physical Modeling ports and connection lines. As a result, the output variables of most SimPowerSystems blocks are not available in the variable description file.

Run-time issues

Parameter access

Relevance

- MATLAB Releases: All relevant
- dSPACE Platforms: All
- ConfigurationDesk, RTI and RTI-MP

Description Due to the structure of SimPowerSystems blocks, they cannot be treated like standard Simulink blocks with respect to instrument layouts in ControlDesk. SimPowerSystems blocks do not contain visible functional information. The simulation data can be accessed with Measurement blocks, which receive data using From / GoTo blocks. The data are sent from a Powergui block.

Stateflow

General limitations

Using RTLib functions with Stateflow

Relevance

- MATLAB Releases: All relevant
- dSPACE Platforms: All
- RTI and RTI-MP

Description Calling RTLib functions (e.g. I/O access) in states and transitions of a Stateflow chart is not recommended. If I/O access is required from within a state chart, we recommend handling this via S-functions that are placed in function-call subsystems, and triggering these subsystems by event outputs of the state charts.

Variable description file issues**Accessible parameters via variable description file****Relevance**

- MATLAB Releases: R2012a R2012b
- dSPACE Platforms: All
- ConfigurationDesk, RTI and RTI-MP

Description There is no propagation of parameter names to code generation. As such, parameters cannot be resolved by their parameter names but are serially numbered (P1, P2, ...).

Accessible states via variable description file**Relevance**

- MATLAB Releases: All relevant
- dSPACE Platforms: All
- RTI-MP

Description Block groups for Stateflow charts contain the outputs to Simulink, Stateflow test points and parameters. The states of Stateflow charts are not accessible via the variable description file. If you need to trace the state activity for a state chart, you can use the Output State Activity option for the states you need to observe.

Global data of all Stateflow charts is available in the State Machine Data group.